

A Framework for Generalization and Transportation of Causal Estimates under Covariate Shift

Apoorva Lal, Wenjing Zheng, Simon Ejdemyr

February 15, 2023

Introduction

- ▶ Scientists, policy-makers, and practitioners care about different kinds of study validity
 - ▶ **Internal** validity: findings are informative about the *population under study*
 - ▶ estimand: **Sample** Average Treatment Effect (SATE)
 - ▶ **External** validity: findings are informative about the *population of interest*
 - ▶ estimand: **Target** Average Treatment Effect (TATE) ; **Population** ATE (PATE)
- ▶ Experiments are a corner solution that prioritizes *Internal* over *External* validity (Egami and Hartman 2022)

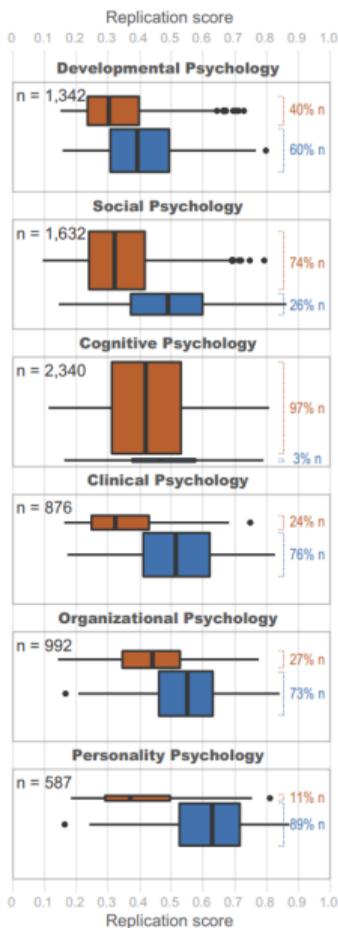
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- ▶ Design based solutions: design to balance in target population (Phan et al. 2021) or balanced sampling (Cytrynbaum 2021)
 - ▶ Limited feasibility in regime with many concurrent experiments
- ▶ **This project:** Framework and package for model-based solutions to bridging (generalizing or transporting) causal estimates to new populations

C All journals



Perspective | [Published: 22 July 2021](#)

Behavioural science is unlikely to change the world without a heterogeneity revolution

[Christopher J. Bryan](#) , [Elizabeth Tipton](#)  & [David S. Yeager](#) 

[Nature Human Behaviour](#) 5, 980–989 (2021) | [Cite this article](#)

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Abstract

In the past decade, behavioural science has gained influence in policymaking but suffered a crisis of confidence in the replicability of its findings. Here, we describe a nascent heterogeneity revolution that we believe these twin historical trends have triggered. This revolution will be defined by the recognition that most treatment effects are heterogeneous, so the variation in effect estimates across studies that defines the replication crisis is to be expected as long as heterogeneous effects are studied without a systematic approach to sampling and moderation. When studied

Data and Estimands

- ▶ Data: $\mathcal{D}_i = (\mathbf{X}_i, S_i, S_i A_i, S_i Y_i)_{i=1}^N$ where
 - ▶ covariates $\mathbf{X}_i \in \mathbb{R}^p$,
 - ▶ treatment $A_i \in \mathcal{A} := \{0, \dots, K\}$,
 - ▶ outcome $Y_i \in \mathbb{R}$,
 - ▶ selection indicator $S_i \in \{0, 1\}$

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- ▶ Observe $(\mathbf{X}_i, A_i, Y_i)_{i=1}^{N_1}$ for observations with $S_i = 1$ (henceforth the *study* sample \mathcal{S}_1)
- ▶ Observe $(\mathbf{X}_i)_{i=N_1+1}^N$ for observations with $S_i = 0$ (henceforth the *target* sample \mathcal{S}_0).
- ▶ The *overall* sample is $\mathcal{S} := \mathcal{S}_1 \cup \mathcal{S}_0$.
- ▶ Two kinds of missing data

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Estimands

Generalizability

$$\mathbb{E}[Y^{a,S=1}]$$

Transportability

$$\mathbb{E}[Y^a | S = 0]$$

Lets us construct causal contrasts for any pair $a, a' \in \mathcal{A}$

Reasoning about extrapolation bias

- ▶ Let $\mathcal{X}_b, p_b(\mathbf{x}), b \in \{s, t\}$ denote Support and Distribution of covariates in **study** and **target**. Bias from naive extrapolation is

$$\begin{aligned} \text{TATE} - \text{SATE} &= \sum_{x \in \mathcal{X}_t} p_t(\mathbf{x})\tau_t(\mathbf{x}) - p_s(\mathbf{x})\tau_s(\mathbf{x}) \\ &= \sum_{x \in \mathcal{X}_t} (p_t(\mathbf{x}) - p_s(\mathbf{x})) \tau(\mathbf{x}) \\ &= \sum_{x \in \mathcal{X}_t} \underbrace{p_s(\mathbf{x})}_{\text{Strata Size}} \underbrace{\left(\frac{p_t(\mathbf{x})}{p_s(\mathbf{x})} - 1 \right)}_{\text{Imbalance}} \underbrace{\tau(\mathbf{x})}_{\text{Heterogeneity}} \end{aligned}$$

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Bias contributions

- ▶ Imbalance in effect-modifying strata \mathbf{x} s.t. $\tau(\mathbf{x}) > 0$
- ▶ Failure of overlap: $p_s(\mathbf{x}) = 0$ but $p_t(\mathbf{x}) > 0$
- ▶ Heterogeneity model instability $\tau_s(\mathbf{x}) \neq \tau_t(\mathbf{x})$
DRO problem (Sahoo, Lei, and Wager 2022; Jeong and Namkoong 2020)

Identification Assumptions

1. Consistency / SUTVA : $Y_i = \sum_{a \in \mathcal{A}} \mathbb{1}_{A_i=a} Y_i^a$

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 - 3.1 Treatment overlap: $0 < \Pr(A = a | \mathbf{X} = \mathbf{x}, S = 1) < 1$
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 - 4.1 $Y^0, \dots, Y^a \perp\!\!\!\perp S | \mathbf{X} = \mathbf{x}$. Ignorability of Selection.
 - 4.2 $\mathbb{E}[Y | A, \mathbf{X}, S = 1] = \mathbb{E}[Y | A, \mathbf{X}, S = 0]$. The outcome model is stable across S strata.

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Under A1,2,3,4.1, the generalization effect is identified. (Dahabreh, Robertson, Tchetgen, et al. 2019; Bia, Huber, and Laffers 2020)

Under A1,2,3,4.2, the transportation effect is identified. (Dahabreh, Robertson, Steingrimsson, et al. 2020; Josey et al. 2021)

Estimator Structure

Augmented Augmented IPW influence function (uncentered)

$$\psi^a = \overbrace{\underbrace{\mu^{(a)}(\mathbf{X}_i)}_{\text{Outcome Model}}}^{\text{Imputation}} + \overbrace{\underbrace{\underbrace{\gamma_i}_{S_i/\rho(\mathbf{X}_i)}_{\text{Sel Wt}} \underbrace{\omega_i}_{\mathbb{1}_{A_i=a}/\pi^a(\mathbf{X}_i)}_{\text{Prop Wt}}}_{\text{Reweighted Residuals}} \underbrace{(Y_i - \mu^{(a)}(\mathbf{X}_i))}_{\text{Residual}}}_{\text{Reweighted Residuals}}$$

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- ▶ Difference between ψ^a and $\psi^{a'}$ estimates causal contrasts (Robins et al 1994, Newey 1994, Hahn 1998, Cattaneo 2010)
- ▶ Estimation: *put hats on* - Nuisance functions estimated by flexible nonparametric regression (L1/L2 reg, random forest, boosting) using cross-fitting
- ▶ Construct observation level influence function (=: doubly robust score)
- ▶ Average over target sample for point estimate, standard deviation for confidence interval

Estimators

| | Generalization $\sum_x \mathbb{E}[Y A = a, S = 1, \mathbf{X}] P(\mathbf{X})$ | Transportation $\sum_x \mathbb{E}[Y A = a, S = 1, \mathbf{X}] P(\mathbf{X} S = 0)$ |
|------|--|---|
| OM | $\frac{1}{n} \sum_i \hat{\mu}^a(\mathbf{X}_i)$ | $\frac{1}{ S_0 } \sum_i (1 - S_i) \hat{\mu}^a(\mathbf{X}_i)$ |
| ISW | $\frac{1}{n} \sum_i \frac{S_i}{\hat{\rho}(\mathbf{X}_i)} \frac{\mathbb{1}_{A=a}}{\hat{\pi}^a(\mathbf{X}_i)} Y_i$ | $\frac{1}{n} \sum_i \frac{1}{\widehat{\mathbb{E}}[S_i=0]} \frac{S_i(1-\hat{\rho}(\mathbf{X}_i))}{\hat{\rho}(\mathbf{X}_i)} \frac{\mathbb{1}_{A=a}}{\hat{\pi}^a(\mathbf{X}_i)} Y_i$ |
| AISW | $\frac{1}{n} \sum_i \hat{\mu}^a(\mathbf{X}_i) + \frac{S_i}{\hat{\rho}(\mathbf{X}_i)} \frac{\mathbb{1}_{A=a}}{\hat{\pi}^a(\mathbf{X}_i)} (Y_i - \hat{\mu}^a(\mathbf{X}_i))$ | $\frac{1}{n} \sum_i \frac{1}{\widehat{\mathbb{E}}[S_i=0]} \left((1 - S_i) \hat{\mu}^a(\mathbf{X}_i) + \frac{S_i(1-\hat{\rho}(\mathbf{X}_i))}{\hat{\rho}(\mathbf{X}_i)} \frac{\mathbb{1}_{A=a}}{\hat{\pi}^a(\mathbf{X}_i)} (Y_i - \hat{\mu}^a(\mathbf{X}_i)) \right)$ |

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- ▶ Outcome modelling (OM), Inverse Selection Weighting (ISW), and Augmented Inverse Selection Weighting (AISW)
- ▶ Target population
- ▶ Implemented in ateGT

Balancing weights

- ▶ goal for selection weights: **balance covariates across study and target**
- ▶ Inverse propensity weighting is indirect: fit $\Pr(S = 1|\mathbf{X})$, then invert
 - ▶ This inversion dramatically inflates errors when selection weights are small
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$$\sum_{i \in \mathcal{S}_1} \gamma_i c_{ij}(X_{ij}) \approx \sum_{i \in \text{target}} \underbrace{c_{ij}(X_{ij})}_{\text{Target moments}}$$

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Dual is easy to solve for certain f s (L2, entropy) as regularized propensity score (Wang and Zubizarreta 2019). Implemented in ateCAL

Incorporating Surrogate Outcomes

- ▶ Suppose further that we observe a short-run outcome Z_i for both $\mathcal{S}_1, \mathcal{S}_0$, but outcome of interest Y_i only for \mathcal{S}_1
 - ▶ This could be because units arrive sequentially and 'mature' at some T period; \mathcal{S}_1 are early adopters

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- ▶ Intermediate outcome Z is said to be a ‘surrogate’ for the long-term outcome
- ▶ Literature on estimation of long-term treatment effects typically relies on variations of strong surrogacy assumption $Y \perp\!\!\!\perp A|Z$ (Athey et al. 2016; Chen and Ritzwoller 2021)

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- ▶ Under analogues of A1-4, Kallus and Mao (2022) derive an influence function for the generalization effect with surrogates

$$\psi = \mu^{(a)}(\mathbf{X}_i) + \underbrace{S_i / \rho(\mathbf{X}_i)}_{\gamma_i} \underbrace{\mathbb{1}_{A_i=a} / \pi^a(\mathbf{X}_i)}_{\omega_i} \left(Y_i - \mu^{(a)}(\mathbf{X}_i) \right) + \omega_i \left(\nu^{(a)}(Z_i, \mathbf{X}_i) - \mu^{(a)}(\mathbf{X}_i) \right) - \tau$$

- ▶ Second residual is information gained from incorporating surrogate outcome in prediction of Y

Characterizing Sensitivity via OVB

- ▶ Identification hinges on A4.1 (selection ignorability).
- ▶ Motivates our estimation strategy via reweighting γ_i
- ▶ Suppose there is an omitted variable U that makes A4.1 hold.
- ▶ True $(\mu, (\pi, \gamma) =: \alpha)$ and feasible $(\mu_s, (\pi, \gamma_s) =: \alpha_s)$ nuisance functions (Chernozhukov et al. 2022) where former includes U as covariate

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$$\alpha_s(\mathcal{D}) = \frac{S_i}{\rho(\mathbf{X}_i)} \left(\frac{\mathbb{1}_{A=a}}{\pi^a(\mathbf{X}_i)} - \frac{\mathbb{1}_{A=a'}}{\pi^{a'}(\mathbf{X}_i)} \right)$$

$$\alpha(\mathcal{D}, U) = \frac{S_i}{\rho(\mathbf{X}_i, U_i)} \left(\frac{\mathbb{1}_{A=a}}{\pi^a(\mathbf{X}_i)} - \frac{\mathbb{1}_{A=a'}}{\pi^{a'}(\mathbf{X}_i)} \right)$$

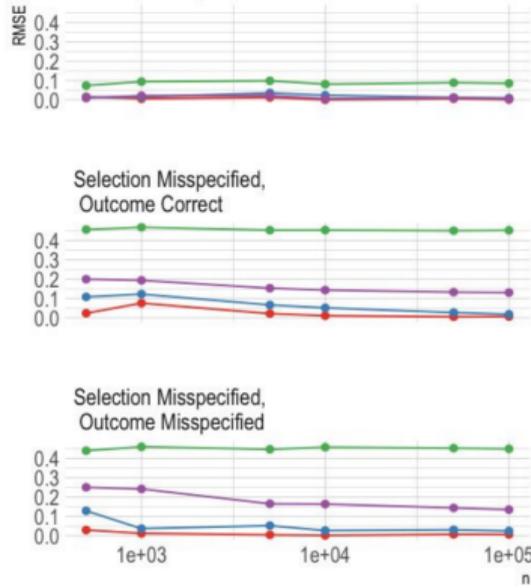
- ▶ Squared Bias can be bounded as $B^2 = S^2 C_Y^2 C_A^2$ where
- ▶ $S^2 := \mathbb{E}(Y - \mu_s)^2 \mathbb{E}\alpha_s^2$ (identifiable)
- ▶ $C_Y^2 = R_{Y - \mu_s \sim \mu - \mu_s}^2$: **conjectured** proportion of residual variance in outcome explained by confounders
- ▶ $C_A^2 = (1 - R_{\alpha \sim \alpha_s}^2) / R_{\alpha \sim \alpha_s}^2$: **conjectured** proportion of residual variance in long RR explained by confounders

Simulation Study

- ▶ **Covariates** $X_1, \dots, X_{10} \sim U[-1, 1]$
- ▶ **Data Generating Process**
 - ▶ $A_i \sim \text{Bernoulli}(0.5)$
 - ▶ $Y_i^* = Y^0(\mathbf{X}_i) + A_i\tau(\mathbf{X}_i)$
 - ▶ $Y_i = Y_i^*$ w.p. $\rho(\mathbf{X})$, else missing
 - ▶ For non-trivial functions $\rho(\mathbf{X})$, there is selection bias and SATE is biased for $\mathbb{E}[\tau(\mathbf{X})]$
- ▶ Vary functional form of
 - ▶ $Y^0(\mathbf{X})$ (Outcome Model)
 - ▶ $\rho(\mathbf{X})$ (Selection Model)

Root Mean Squared Error

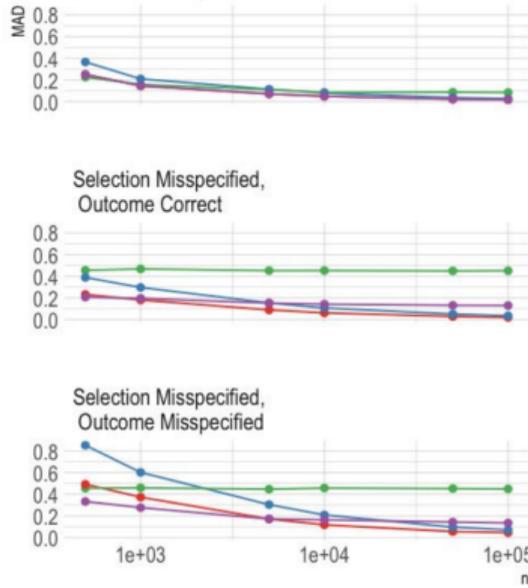
Selection Correct,
Outcome Misspecified



Bias

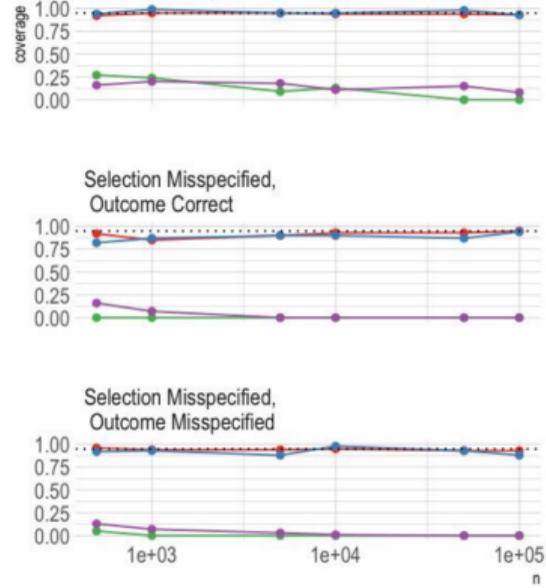
aisw isw naive om

Selection Correct,
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Coverage

Selection Correct,
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Implementation in causalTransportR

- ▶ Main function: ateGT (ATE Generalization or Transportation)
- ▶ Input vectors y , a , s of outcome, treatment, and selection where y , a are missing for $s = 0$
- ▶ Matrix of X of covariates (no missings)
- ▶ Additional arguments for nuisance function estimation

```
ateGT(  
  y,  
  a,  
  X,  
  s = NULL,  
  treatProb = NULL,  
  Z = NULL,  
  nuisMod = c("rlm", "rf"),  
  target = c("generalize", "transport", "insample"),  
  estimator = c("AISW", "ISW", "OM", "CW", "ACW"),  
  hajekize = FALSE,  
  separateMus = TRUE,  
  glmnet_lamchoice = "lambda.min",  
  glmnet_alpha = 1,  
  glmnet_rho_family = "binomial",  
  glmnet_pi_family = "binomial",  
  glmnet_mu_family = "gaussian",  
  glmnet_parl = FALSE,  
  grf_tuneRf = "none",  
  noi = FALSE  
)
```

Conclusion

- ▶ Proposes a multi-treatment framework for causal generalization and transportation
- ▶ provide a performant computational implementation for it in `causalTransportR::ateGT`
 - ▶ calibrated generalization for when only summary statistics are available for target (`ateCAL`)
 - ▶ poststratification weights using fast fixed effects regressions (`ateGTreg`)
- ▶ Future work: more work on sensitivity analyses
 - ▶ Partial identification for generalization using marginal sensitivity model (Nie, Imbens, and Wager 2021) or Proportion with confounding (Kennedy and Bonvini 2021)
 - ▶ Estimate how different the population needs to be from the experimental sample to explain away the effect (Devaux and Egami 2022)

Thanks!

software: <https://github.com/apoorvalal/causalTransportR>

email: apoorval@stanford.edu

website: apoorvalal.github.io

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