

Augmented Balancing Estimators of the Average Treatment Effect on the Treated in cross-sectional and panel designs

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SME, work done at Stanford

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Overview

Introduction

Framework

- Propensity Scores vs Balancing Weights

- Cross-section

- Two-periods

- Panel Data

Optional: Simulation Studies

- Cross-section

- Two-periods

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Introduction

- ▶ Explosion of methods in observational causal inference methods in the last decade that aim to weaken identification assumptions, relax functional form assumptions, and estimate new quantities
 - ▶ Double Machine Learning (Chernozhukov, Chetverikov, et al. 2018) is now well known and hinges on *selection on observables*: the treatment is as good as randomly assigned conditional on observed covariates
 - ▶ With repeated measurements, we can relax this and allow for *selection on unobservables* using Difference-in-Differences, or Synthetic Control (and friends)

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- ▶ **This Paper**: Express popular research designs in a shared augmented balancing form, extensive simulation studies to guide empirical practice, software abal
- ▶ Complementary practitioner's guide to common framework for combining flexible models for causal problems : Ben-Michael, Feller, and Rothstein (2021), Shen et al. (2022), and Bruns-Smith et al. (2023)

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The Estimand

- ▶ $(Y_i, W_i, \mathbf{X}_i)_{i=1}^N \in \mathbb{R} \times \{0, 1\} \times \mathcal{X} \subseteq \mathbb{R}^d$. Corresponding covariate distributions for treatment \mathcal{T} and control \mathcal{C} .
- ▶ ATE ($\mathbb{E} [Y^{(1)} - Y^{(0)}]$) and ATT ($\mathbb{E} [Y^{(1)} - Y^{(0)} \mid W = 1]$) are both substantively meaningful estimands, and require related but distinct identification assumptions

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- ▶ Analogous ‘canonicalization’ problem: generalise from A/B test to a target distribution: Estimate $\mathbb{E} [Y^{(w)} \mid S = 0]$ (bridgerton)

Propensity Scores vs Balancing Weights

- ▶ One way to compute $\hat{\xi}$ is through reweighting $\hat{\mathbb{E}}_{\mathcal{C}} \left(\frac{dT}{d\mathcal{C}}(X)Y \right)$
- ▶ Density ratio $\frac{dT}{d\mathcal{C}}(X)$ is challenging to estimate using plug-in estimation
- ▶ Standard practice: fit model $\pi(\mathbf{X}) = \mathbb{E}[W = 1 \mid \mathbf{X}]$, plug in to construct inverse-pscore weight $\frac{\pi(\mathbf{X})}{1-\pi(\mathbf{X})}$

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- ▶ Alternative: directly estimate weights to minimize covariate imbalance
 - ▶ ‘Automatic’ estimation of the Riesz Representer (Hirshberg and Wager 2021; Chernozhukov, Newey, and Singh 2022)

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$$\min_{\gamma} \overbrace{h_{\zeta}(\mathbf{X}_1 - \mathbf{X}'_0 \gamma)}^{\text{Balance}} + \sum_{i \in \mathcal{C}} \overbrace{f(\gamma_i)}^{\text{Dispersion}}$$
$$\text{s.t. } \sum_{i \in \mathcal{C}} \gamma_i = 1$$

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For convex $f(\cdot)$, dual is easy to solve as regularized propensity score

$$\min_{\alpha, \beta} \sum_{i \in \mathcal{C}} f^*(\alpha + \beta' \mathbf{X}_{i\cdot}) - (\alpha + \beta' \mathbf{X}_1) + h_{\zeta}^*(\beta)$$
$$\hat{\gamma}^* = f^{*'}(\hat{\alpha} + \hat{\beta}' \mathbf{X}_i)$$

rsw implementation with ADMM

Cross Sectional: Identification and Estimation

Identification Assumptions

▶ SUTVA:

$$Y_i = W_i Y^{(1)} + (1 - W_i) Y^{(0)}$$

▶ Unconfoundedness: $Y^{(0)} \perp\!\!\!\perp W | \mathbf{X}_i$

▶ Overlap: $\Pr(W = 1 | \mathbf{X}) < 1$

Share of treated observations

$$\hat{\rho} := \Pr(W = 1)$$

Cross Sectional: Identification and Estimation

Estimators

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▶ **Outcome Modelling**

$$\hat{\xi}^{\text{OM}} := \frac{1}{n_t} \sum_{i \in \mathcal{T}} \hat{\mu}^{(0)}(\mathbf{X}_i)$$

▶ **Reweighting** $\hat{\xi}^{\text{wt}} = \sum_{i \in \mathcal{C}} \gamma_i Y_i$

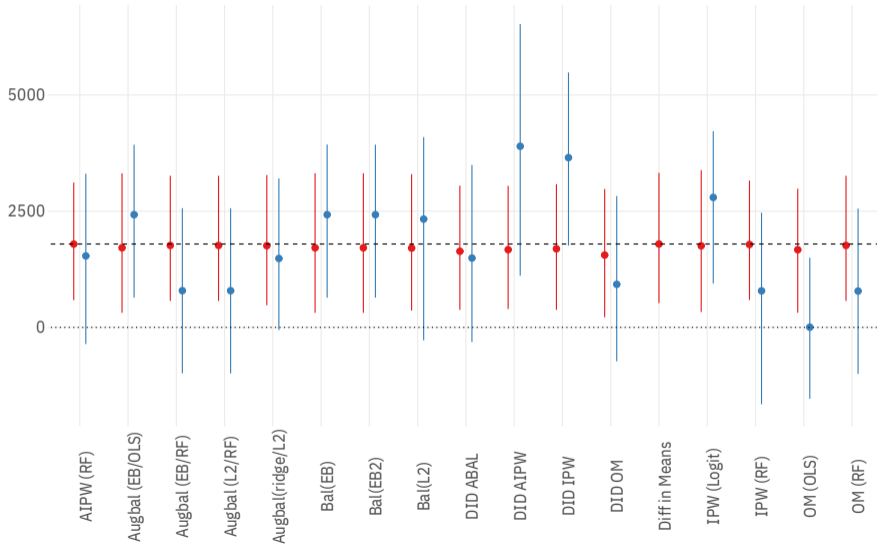
▶ **Augmented Balancing**

$$\hat{\xi}^{\text{AUGBAL}} = \underbrace{\frac{1}{\hat{\rho}} \sum_{i \in \mathcal{T}} \hat{\mu}^{(0)}(\mathbf{X}_i)}_{\text{Reg}} + \underbrace{\frac{1}{\hat{\rho}} \frac{1}{n} \sum_{i \in \mathcal{C}} \gamma_i \{Y_i - \hat{\mu}^{(0)}(\mathbf{X}_i)\}}_{\text{Reweighted Residuals}}$$

Estimating the ATT on Lalonde (1986) JTPA Data

Dashed line denotes difference in means estimate from the experiment

Experiment PSID (Obs)



Formal Properties: The role of augmentation

Following Ben-Michael, Feller, Hirshberg, et al. (2021), we can decompose errors

$$\begin{aligned}
 \widehat{\xi}^{\text{WT}} - \xi &= \overbrace{\frac{1}{n} \sum_i (1 - W_i) \widehat{\gamma}_i \mu^{(0)}(\mathbf{x}_i) - \frac{1}{n} \sum_i W_i \mu^{(0)}(\mathbf{x}_i)}^{\text{Bias from Imbalance}} - \overbrace{\frac{1}{n} \sum_{i=1}^n (1 - W_i) \widehat{\gamma}_i \varepsilon_i}^{\text{Noise}} + \overbrace{\frac{1}{n} \sum_{i=1}^n W_i \mu^{(0)}(\mathbf{x}_i) - \xi}^{\text{Sampling}} \\
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If our outcome model isn't totally useless, **regression error** will be easier to balance than **the unknown regression**. $\hat{\mu}^{(0)}$ and $\hat{\gamma}_i$ play complementary roles: regression could soak up strong signals and weights pick up higher order ones.

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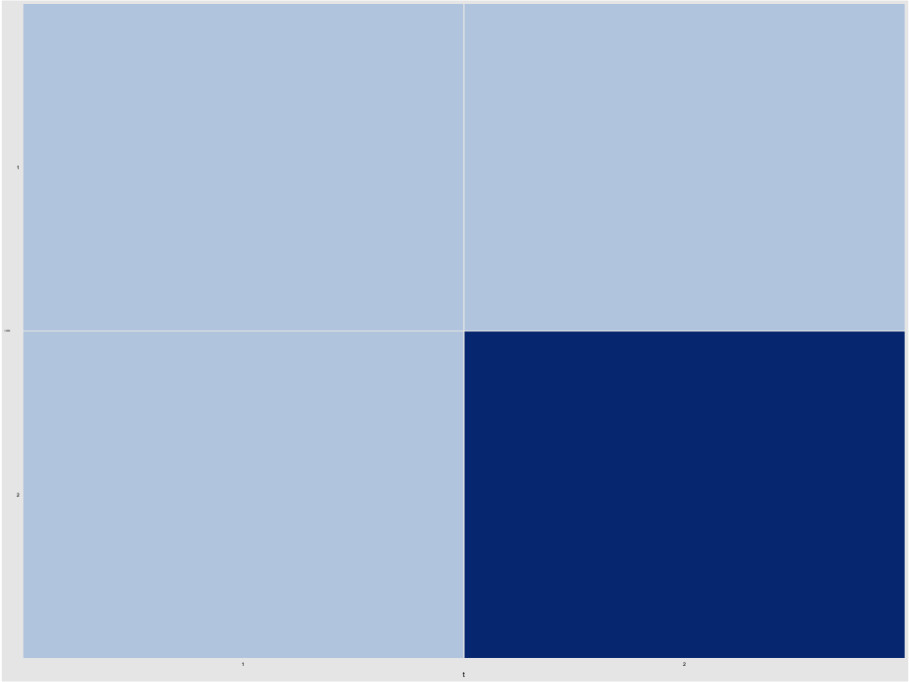
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Consistent and Asymptotically Normal, Semiparametrically efficient, admits to standard variance formula (Ben-Michael, Feller, Hirshberg, et al. 2021)[Appdx A]



Difference in Differences: Identification

- ▶ Unconfoundedness is often not credible. We want to allow for level differences in $Y^{(0)}$ across treatment and control due to unobserved factors
- ▶ Two periods, $(Y_{i1}, Y_{i0}, W_i, \mathbf{X}_i)_{i=1}^N$. Treatment W applies in second period
- ▶ Estimator $\hat{\xi} := \widehat{\mathbb{E}} \left[Y_{i1}^{(0)} \mid W = 1 \right]$

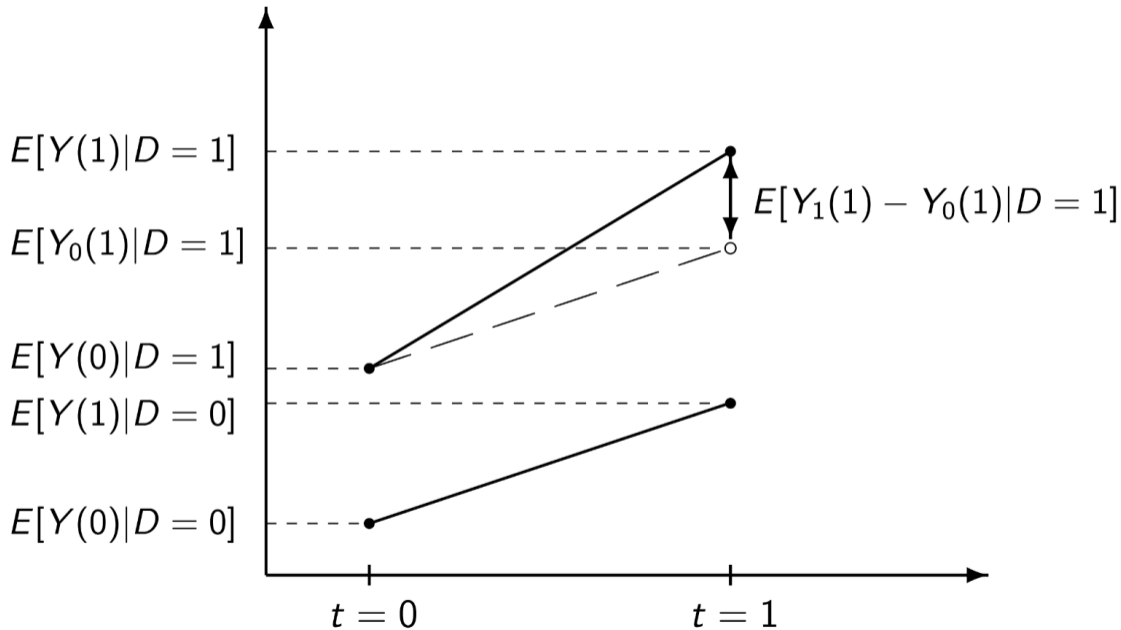
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- ▶ Identification Assumptions

1. No anticipation $\mathbb{E} [Y_{i0} \mid W_i = 1] = \mathbb{E} \left[Y_{i0}^{(0)} \mid W_i = 0 \right]$

2. Conditional Parallel Trends

$$\mathbb{E} \left[Y_{i1}^{(0)} - Y_{i0}^{(0)} \mid W = 1, \mathbf{X} \right] = \mathbb{E} \left[Y_{i1}^{(0)} - Y_{i0}^{(0)} \mid W = 0, \mathbf{X} \right]$$



Difference in Differences: Estimation

► Outcome Modelling

$$\widehat{\xi}^{\text{DID}} = \underbrace{\frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i0}}_{\text{Baseline outcome for treated}} + \underbrace{\frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} \left(\overbrace{Y_{i1} - Y_{0i}}^{=:\Delta_i} \right)}_{\text{Trend for control}}$$

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► Reweighting (Abadie (2005) proposes IPW with $\gamma_i = \pi(\mathbf{X}_i)/(1 - \pi(\mathbf{X}_i))$)

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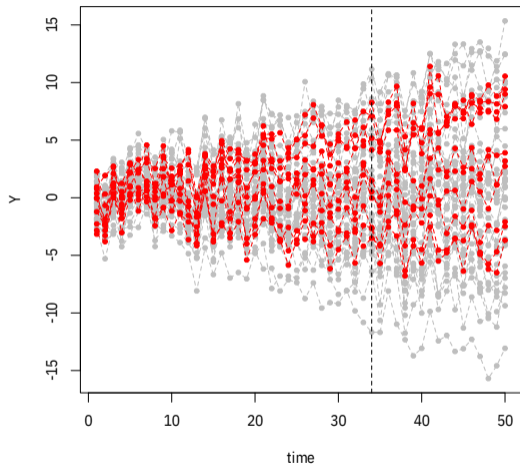
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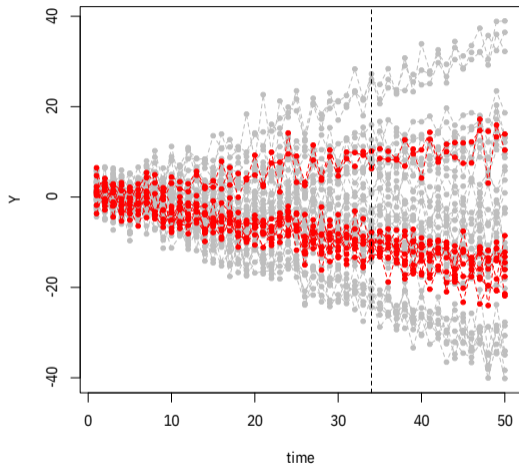
- ▶ Augmented Balancing (with $\widehat{\mu}^0(\mathbf{X}_i) = \mathbb{E}[\Delta_i \mid \mathbf{X}_i = \mathbf{x}_i, W_i = 0]$)

$$\widehat{\xi}^{\text{AUGBAL DID}} = \frac{1}{|\mathcal{T}|} \sum_{i \in \mathcal{T}} Y_{i0} - \widehat{\mu}^0(\mathbf{X}_i) + \frac{1}{|\mathcal{C}|} \sum_{i \in \mathcal{C}} \gamma_i (\Delta_i - \widehat{\mu}^0(\mathbf{X}_i))$$

50 units, 50 periods, 10 clusters
10 treated, 34 pre-treatment periods



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Panel Data: Identification

- ▶ Data: $(\mathbf{Y}_{it}, \mathbf{W}_{it})_{i=1}^N, t \in [T]$. Absorbing treatment, one-shot adoption by N_1 units at time $T_0 + 1$
- ▶ Commonly used under analogous assumptions to 2-period DID
 - ▶ ‘Long’ Parallel Trends
$$\mathbb{E} \left[Y_{it}^{(0)} - Y_{it'}^{(0)} | W_i = 1 \right] = \mathbb{E} \left[Y_{it}^{(0)} - Y_{it'}^{(0)} | W_i = 0 \right] \quad \forall t \neq t'$$
 - ▶ Frequently paired with corresponding representation for untreated PO
$$Y_{it}^{(0)} = \alpha_i + \gamma_t + \varepsilon_{it}$$
 (Liu, Wang, and Xu 2021; Borusyak, Jaravel, and Spiess 2022)

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- ▶ Alternate identification assumptions
 1. Latent Factor Model: $Y_{it}^{(0)} = \sum_{j=1}^J \phi_{ij} \mu_{jt} + \varepsilon_{it}$ with unknown time-varying factors $\boldsymbol{\mu}_t = \{\mu_{jt}\} \in \mathbb{R}^T, j = 1, \dots, J$ and unknown unit loadings $\phi_i \in \mathbb{R}^J$ (Abadie, Diamond, and Hainmueller 2010; Xu 2017)
 2. Unconfoundedness given history: $Y_{it}^{(0)} \perp\!\!\!\perp W_i | \mathbf{Y}_{i,1:T_0} \quad \forall t > T_0$ (Ben-Michael, Feller, and Rothstein 2021)

Panel Data: Estimation inference

$$\left(\begin{array}{cccc|c} Y_{1,1} & Y_{1,2} & \dots & Y_{1,T_0} & Y_{1,T} \\ Y_{2,1} & Y_{2,2} & \dots & Y_{2,T_0} & Y_{2,T} \\ \vdots & & & & \vdots \\ Y_{N_0,1} & Y_{N_0,2} & \dots & Y_{N_0,T_0} & Y_{N_0,T} \\ \hline \vdots & & & & ? \\ Y_{N,1} & Y_{N,2} & \dots & Y_{N,T_0} & ? \end{array} \right)$$
$$=: \left(\begin{array}{c|c} \mathbf{X}^0 & \mathbf{y}^n \\ \mathbf{X}^1 & ? \end{array} \right)$$

(Athey et al. [2021](#)) formalism:

SC fit $\mathbf{X}^1 \sim \mathbf{X}^0$ (Vertical Regression)

Autoregressive models fit $\mathbf{y}^n \sim \mathbf{X}^0$

(Horizontal Regression)

Some outcome models (DFM, MC) fit both.

Panel Data: Estimation inference

Outcome Modelling : $\hat{\xi}^{\text{HR}} = \hat{\mu}^0(\mathbf{X}^1)$

Balancing

$\hat{\xi}^{\text{VR}} = \langle \hat{\gamma}, \mathbf{y}^n \rangle$ where

$$\hat{\gamma} = \underset{\gamma \in \Delta_{|C|-1}}{\operatorname{argmin}} h(\gamma) \text{ s.t. } \langle \gamma, \mathbf{X}^0 \rangle \approx \bar{\mathbf{X}}^1 + \mu$$

Augmented Balancing

$$\begin{aligned} \hat{\xi}^{\text{AugBal}} &= \hat{\mu}^0(\mathbf{X}, \mathbf{y}_n) \\ &+ \sum_{i \in \mathcal{C}, t > T_0} \hat{\gamma}_i (Y_{it} - \hat{\mu}(\mathbf{X}, \mathbf{y}_n)) \end{aligned}$$

$$\begin{pmatrix} Y_{1,1} & Y_{1,2} & \dots & Y_{1,T_0} & | & Y_{1,T} \\ Y_{2,1} & Y_{2,2} & \dots & Y_{2,T_0} & | & Y_{2,T} \\ \vdots & & & & | & \vdots \\ Y_{N_0,1} & Y_{N_0,2} & \dots & Y_{N_0,T_0} & | & Y_{N_0,T} \\ \hline \vdots & & & & | & ? \\ Y_{N,1} & Y_{N,2} & \dots & Y_{N,T_0} & | & ? \end{pmatrix} =: \left(\begin{array}{c|c} \mathbf{X}^0 & \mathbf{y}^n \\ \mathbf{X}^1 & ? \end{array} \right)$$

(Athey et al. 2021) formalism:

SC fit $\mathbf{X}^1 \sim \mathbf{X}^0$ (Vertical Regression)

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SDID: simplex regression for both

Augsynth: ridge regression for both

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SDID: simplex regression for both

Augsynth: ridge regression for both

Alternative: Matrix Completion + Entropy

$$\begin{pmatrix} Y_{1,1} & Y_{1,2} & \dots & Y_{1,T_0} & | & Y_{1,T} \\ Y_{2,1} & Y_{2,2} & \dots & Y_{2,T_0} & | & Y_{2,T} \\ \vdots & & & & | & \vdots \\ Y_{N_0,1} & Y_{N_0,2} & \dots & Y_{N_0,T_0} & | & Y_{N_0,T} \\ \hline \vdots & & & & | & ? \\ Y_{N,1} & Y_{N,2} & \dots & Y_{N,T_0} & | & ? \end{pmatrix} =: \left(\begin{array}{c|c} \mathbf{X}^0 & \mathbf{y}^n \\ \mathbf{X}^1 & ? \end{array} \right)$$

(Athey et al. 2021) formalism:

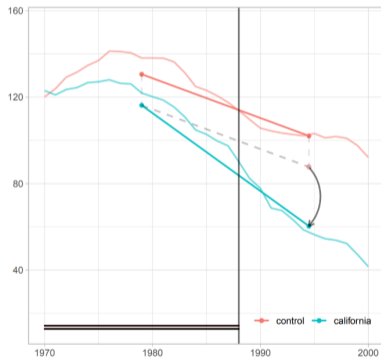
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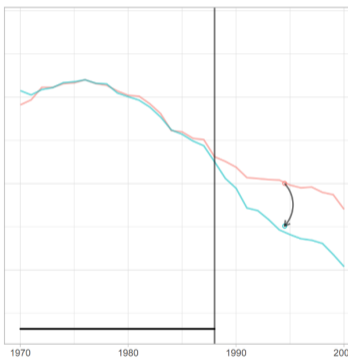
(Horizontal Regression)

Some outcome models (DFM, MC) fit both.

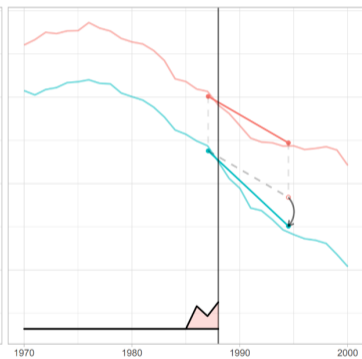
Diff. in Differences



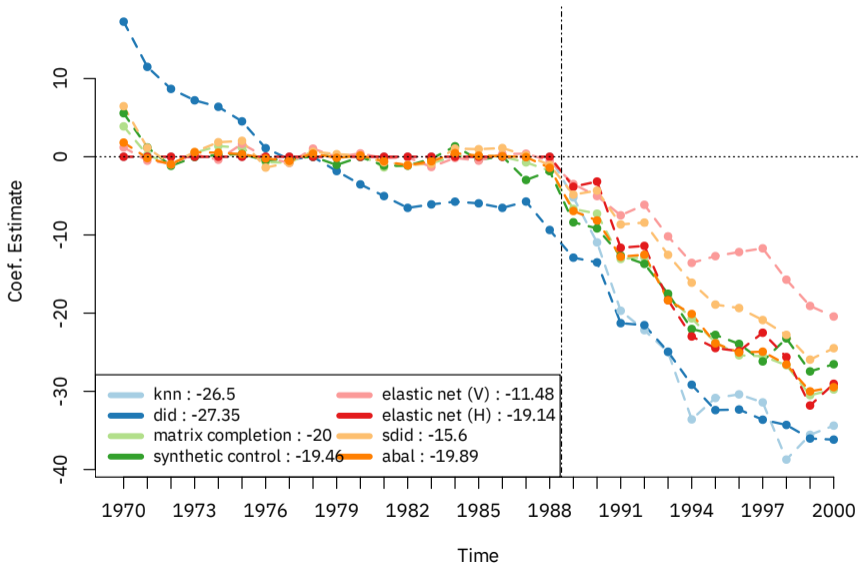
Synthetic Control



Synth. Diff. in Diff.



Event Study Estimates California Prop 99



Inference

- ▶ For cross-sectional and two-period estimators, we have a conventional score function that can be used to construct confidence intervals
 - ▶ With flexible nuisance models, cross-fitting required for valid inference
 - ▶ With a restricted class of models (Donsker or ‘simple-enough’ (leave-out stability (Chen, Syrgkanis, and Austern 2022))), can use full data
- ▶ For panel data, analogous techniques aren’t available. Bootstrap or Jackknife shown to work well (Arkhangelsky et al. 2020)
 - ▶ With single treated unit, inference procedure is non-standard: use permutation tests or conformal methods

Overview

Introduction

Framework

Propensity Scores vs Balancing Weights

Cross-section

Two-periods

Panel Data

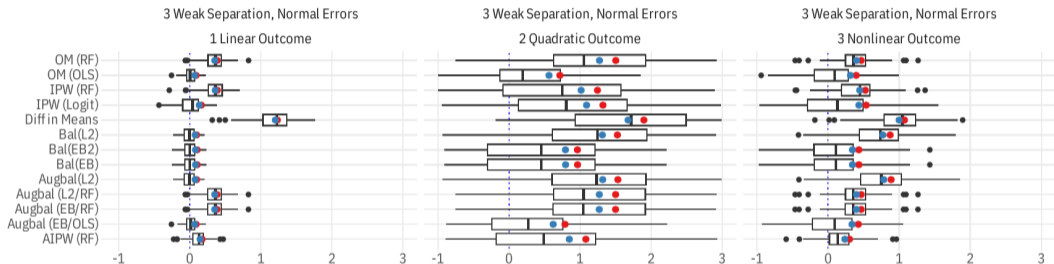
Optional: Simulation Studies

Cross-section

Two-periods

Panel Data

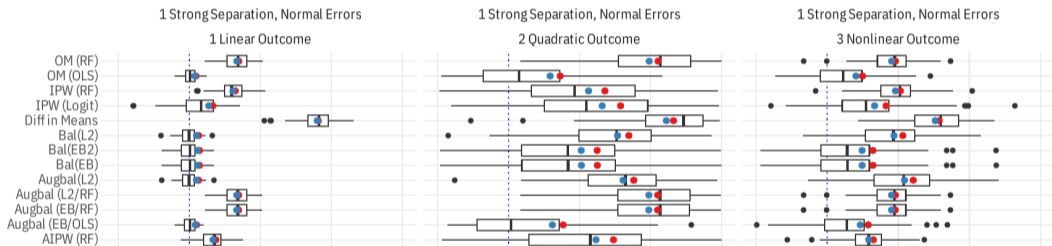
Cross-sectional Simulation: Good overlap



True effect of 0.

Extension of Froelich(2007), Hainmueller (2012)

Cross-sectional Simulation: Poor overlap



Cross-Sectional : ACIC 2016 DGP

ACIC (2016) DGPs (Dorie et al. 2019):
4802 observations and 58 covariates.
100 replications of 77 simulation settings that vary

- ▶ **Treatment model** $\in \{ \text{Linear, polynomial, step} \}$
- ▶ **Response model** $\in \{ \text{Linear, exponential, step} \}$
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- ▶ **Treated %**

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- ▶ **Treated %**

	Bias	RMSE
OLS	0.6146	0.7435
IPW	0.6302	2.3247
AIPW	0.1516	0.2070
EB1	0.4951	0.6461
EB2	0.2578	0.3689
HBAL	3.2490	3.8954
balHD	0.4585	0.5904
AugBalE	0.2001	0.3344

Previously, both L2 and ebal only successfully computed $\approx 60\%$ (Cousineau et al (2022)).

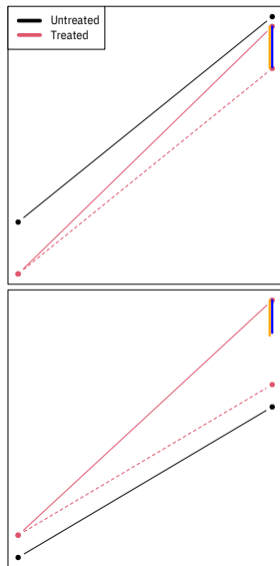
ebal performance in high dimensions

DiD simulation setup

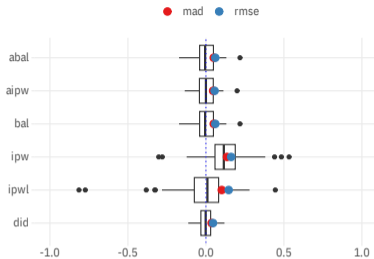
- ▶ p -vector $\mathbf{X}_i \sim \mathcal{N}(0, \Sigma)$ where Σ follows Toeplitz form with entries $0.5^{0:(p-1)}$ (correlated covariates)
- ▶ $W_i \sim \text{Bern}(\Lambda(\mathbf{X}'_i \gamma))$, γ sparse $\cup [-1, 1]$
- ▶ Baseline outcomes $Y_{(w)i}(0)$ generated $\mathbf{X}'_i \boldsymbol{\beta}^{(w)} + \varepsilon_i$ with $\boldsymbol{\beta}^{(w)}$ sparse
- ▶ Trend $Y_{0i}(1) - Y_{0i}(0)$ generated $\mathbf{X}'_i \boldsymbol{\beta}^\Delta + \varepsilon_i$ (where $\boldsymbol{\beta}^\Delta = 0$ for PT)
- ▶ Estimand: ATT in the 2nd period

DiD simulation setup

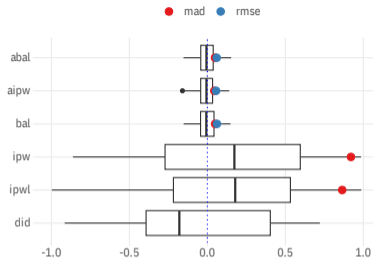
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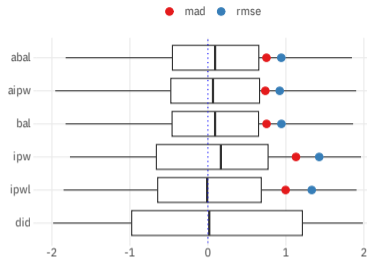
N = 500, p = 10
Uncond PT



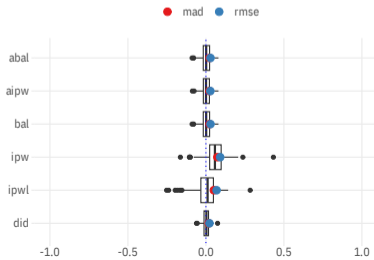
N = 500, p = 10
Cond PT



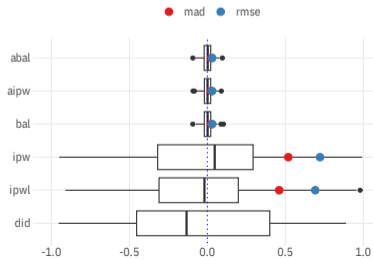
N = 500, p = 10
Cond PT, Misspecified



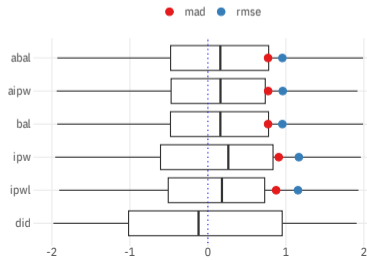
N = 2000, p = 10
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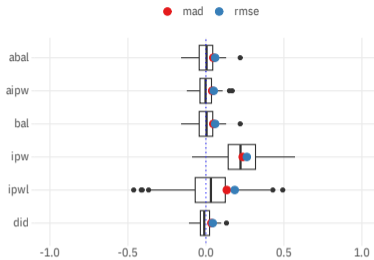
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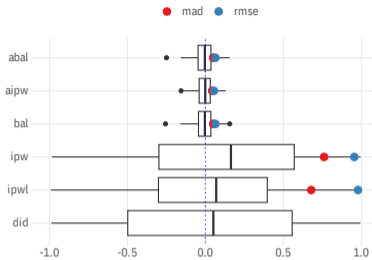
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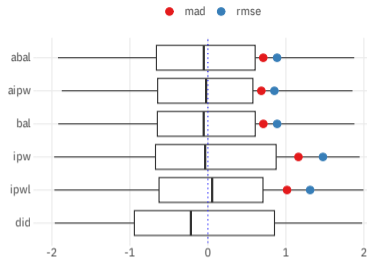
N = 500, p = 30
Uncond PT



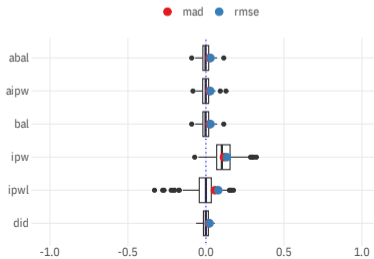
N = 500, p = 30
Cond PT



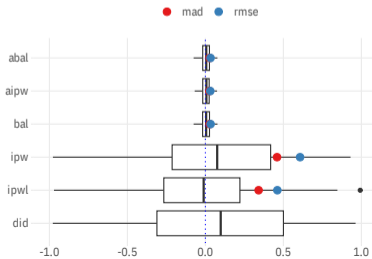
N = 500, p = 30
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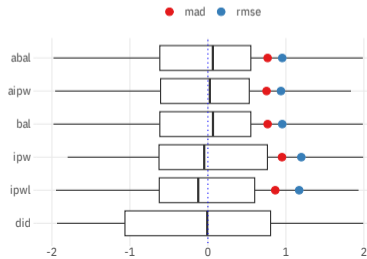
N = 2000, p = 30
Uncond PT



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Cond PT, Misspecified

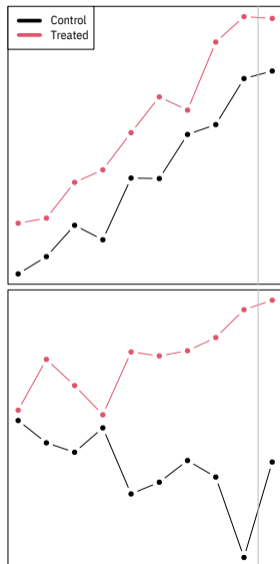


Panel Simulation Setup

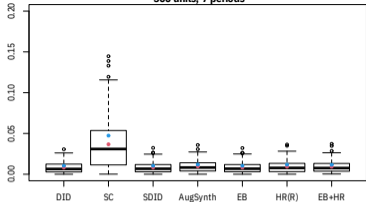
- ▶ N units, T periods
- ▶ Single unknown factor: $\mu_i \sim \mathcal{N}(i/N - 0.5, 0.5)$
- ▶ Treatment: $W_i \sim \text{Bern}(\Lambda(\mu_i))$
- ▶ Outcome:
 - ▶ **parallel trends:** $Y_{it} = \mu_i + 0.1t + \varepsilon_i, \varepsilon_i \sim \mathcal{N}(0, \sigma)$
 - ▶ **time trends:** $Y_{it} = \mu_i \alpha_t t + \varepsilon_i, \varepsilon_i \sim \mathcal{N}(0, \sigma), \alpha_t \sim \text{U}[l, u]$
 - ▶ Later: ARIMA with dynamics in both Y_{it}, ε_{it}
- ▶ Estimand: ATT in the last period (true effect is 0)

Panel Simulation Setup

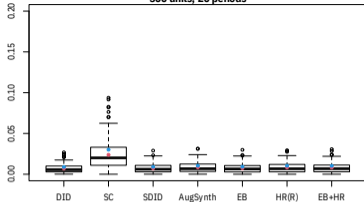
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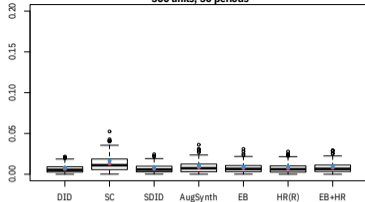
Parallel Trends, Low Noise
500 units, 7 periods



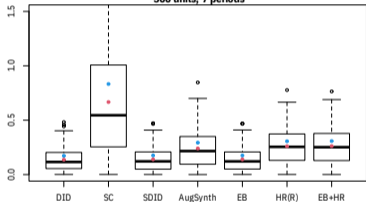
Parallel Trends, Low Noise
500 units, 20 periods



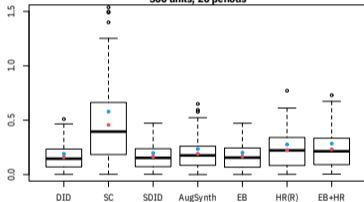
Parallel Trends, Low Noise
500 units, 50 periods



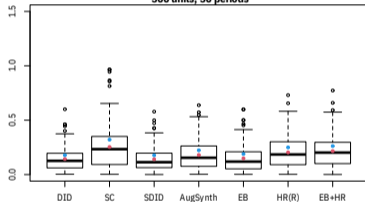
Parallel Trends, Medium Noise
500 units, 7 periods



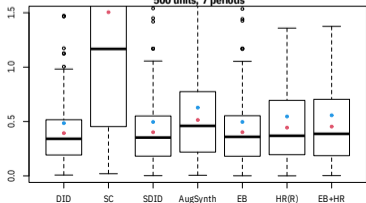
Parallel Trends, Medium Noise
500 units, 20 periods



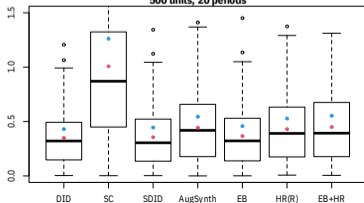
Parallel Trends, Medium Noise
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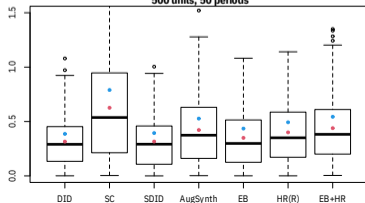
Parallel Trends, High Noise
500 units, 7 periods



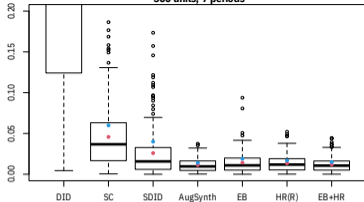
Parallel Trends, High Noise
500 units, 20 periods



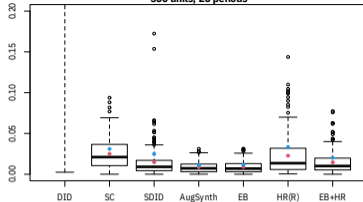
Parallel Trends, High Noise
500 units, 50 periods



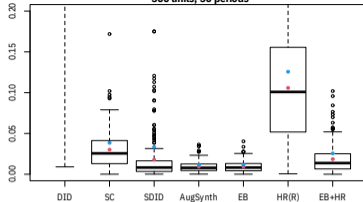
Non-Parallel Trends, Low Noise
500 units, 7 periods



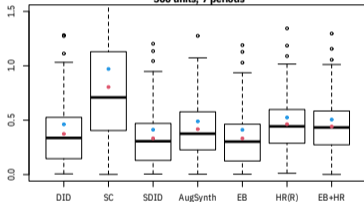
Non-Parallel Trends, Low Noise
500 units, 20 periods



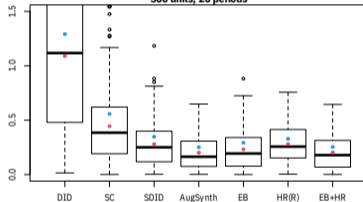
Non-Parallel Trends, Low Noise
500 units, 50 periods



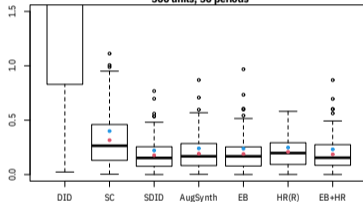
Non-Parallel Trends, Medium Noise
500 units, 7 periods



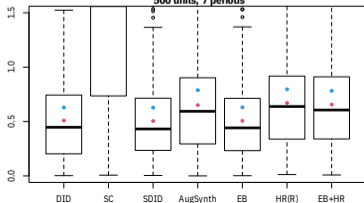
Non-Parallel Trends, Medium Noise
500 units, 20 periods



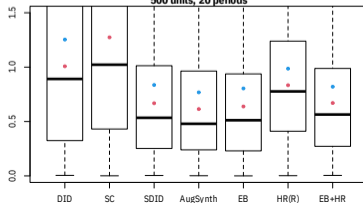
Non-Parallel Trends, Medium Noise
500 units, 50 periods



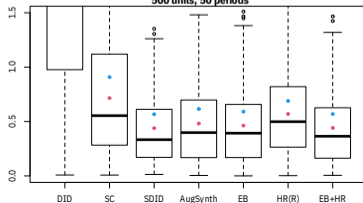
Non-Parallel Trends, High Noise
500 units, 7 periods



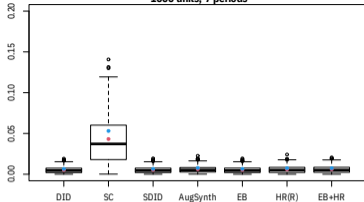
Non-Parallel Trends, High Noise
500 units, 20 periods



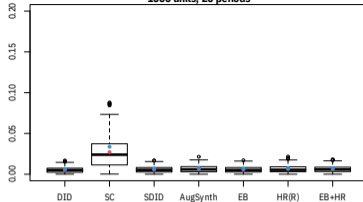
Non-Parallel Trends, High Noise
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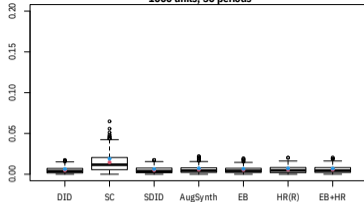
Parallel Trends, Low Noise
1000 units, 7 periods



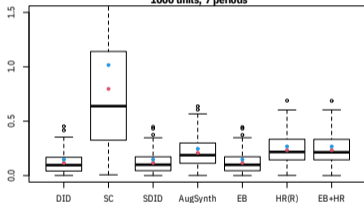
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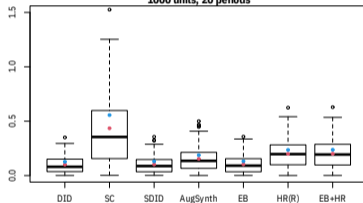
Parallel Trends, Low Noise
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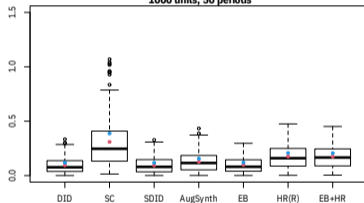
Parallel Trends, Medium Noise
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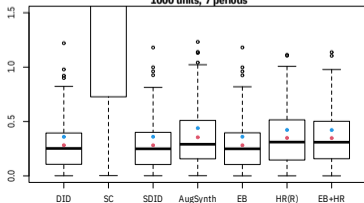
Parallel Trends, Medium Noise
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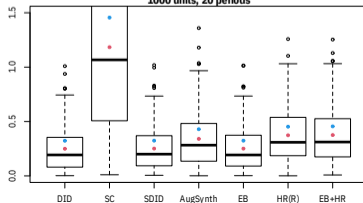
Parallel Trends, Medium Noise
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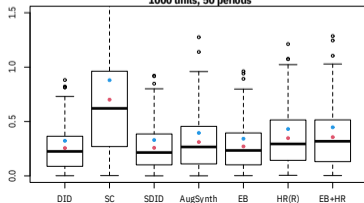
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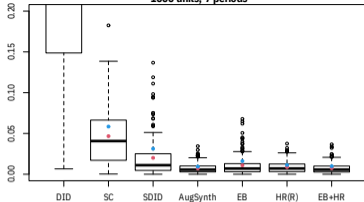
Parallel Trends, High Noise
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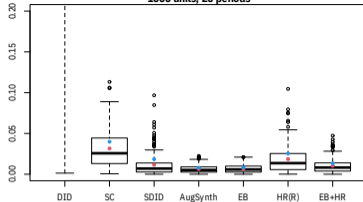
Parallel Trends, High Noise
1000 units, 50 periods



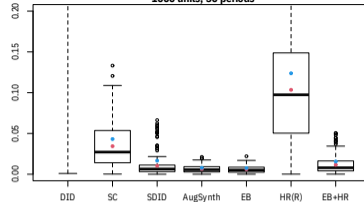
Non-Parallel Trends, Low Noise
1000 units, 7 periods



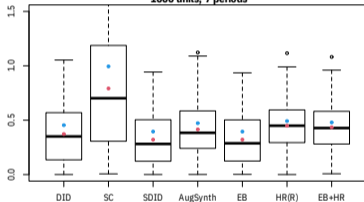
Non-Parallel Trends, Low Noise
1000 units, 20 periods



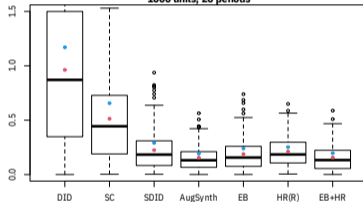
Non-Parallel Trends, Low Noise
1000 units, 50 periods



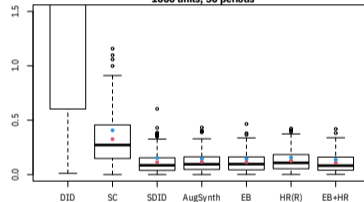
Non-Parallel Trends, Medium Noise
1000 units, 7 periods



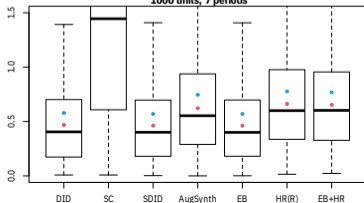
Non-Parallel Trends, Medium Noise
1000 units, 20 periods



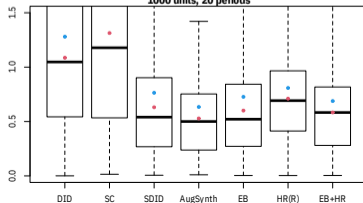
Non-Parallel Trends, Medium Noise
1000 units, 50 periods



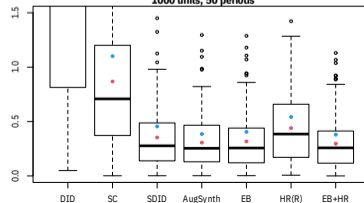
Non-Parallel Trends, High Noise
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Non-Parallel Trends, High Noise
1000 units, 20 periods



Non-Parallel Trends, High Noise
1000 units, 50 periods



The choice of loss function for Panel Balancing

$$\min_{\gamma \in \Delta} \overbrace{h_{\zeta}(\mathbf{X}_1 - \mathbf{X}'_0 \gamma)}^{\text{Balance}} + \sum_{i \in \mathcal{C}} \overbrace{f(\gamma_i)}^{\text{Dispersion}}$$

$h_{\zeta}(\cdot)$ fixed to L_2

Penalty for dispersion $f(\cdot)$

consequential

- ▶ SC has no penalisation
- ▶ SDID has theoretically motivated penalisation
- ▶ EB penalises *deviation from uniform weights*: interpolates between DiD and balancing

DGP with factor structure,
 $N = 500, T = 10$; perfect fit

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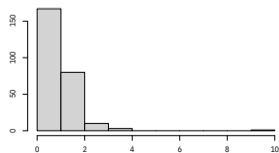
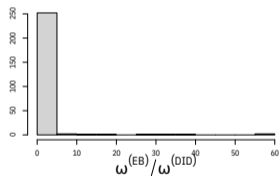
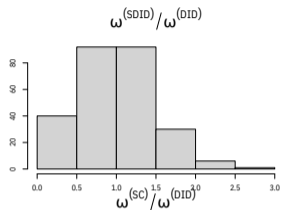
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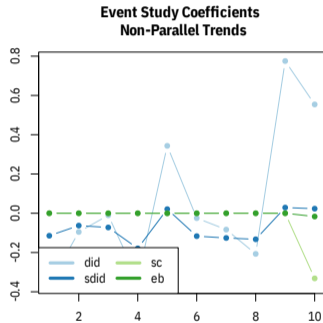
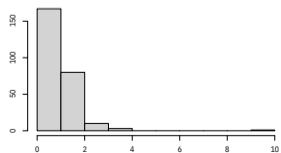
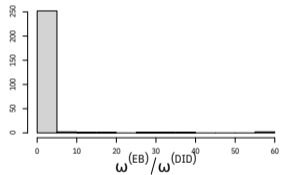
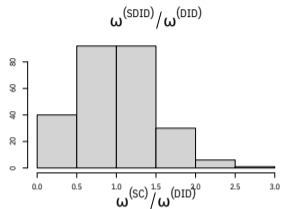
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dilution of weights behaviour from Ferman (2021)

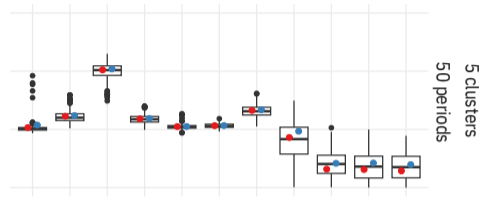
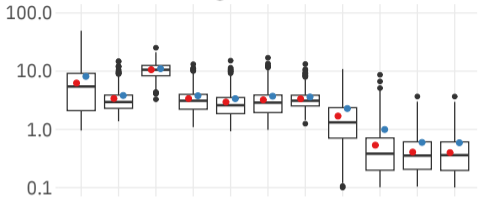
factor recovery

If parallel trends holds

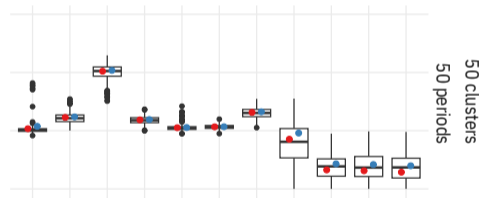
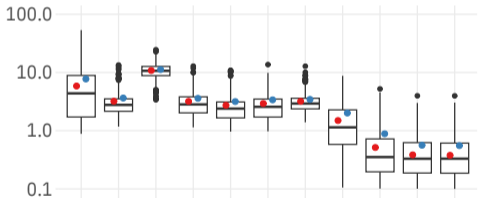
● MAD ● RMSE

Strong Serial Correlation

Weak Serial Correlation



50 clusters
50 periods



50 clusters
50 periods

DFM

KNN

DID

MC

SC

ENET(V)

ENET(H)

SDID

Augbal(HR+VR)

Augbal(MC+VR)

Augbal(MC+Resid)

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Conclusion

- ▶ Flexible models can be judiciously used with reweighting methods to improve the robustness of our estimates to misspecification
- ▶ Increasing consensus on adopting a hybrid structure of combining a performant outcome model with weights that explicitly target sample balance
 - ▶ No feedback is a very strong assumption in panel settings (reversals are common)
 - ▶ Double robustness is heuristic in this setting, since assignment mechanism isn't directly modelled
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- ▶ We propose a common framework for these 'augmented balancing' estimators in three popular designs and perform extensive simulation studies to show that they weakly outperform standard estimators (including AIPW), and provide heuristic understanding of when gains are likely to be particularly large
- ▶ Forthcoming R package `aba1` that uses analogously modular construction to pair flexible outcome models with a fast and numerically stable estimation procedure for balancing weights

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